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# Overcome the Challenges of Using Sub-Milliohm SMD Chip Resistors (Part 1)

Today's low-ohmic-value current-sense resistors have driven downward from milliohms to hundreds of microhms. Working with such low ohmic value, designers face challenges as well as opportunities throughout their design and manufacturing processes.

the s<br>vert<br>use<br>ups<br>actuators th<br>to huge man he simplest and most cost-effective way of converting a measured current to a voltage signal is to use a low-ohmic-value current-sense resistor. The upswing in products containing batteries, motors, or actuators that call for current monitoring or control has led to huge market growth for current-sense chip resistors with values below one ohm over the last two decades.

More recently, though, driven by power-efficiency demands and enabled by low-noise voltage-sense amplifiers, the value range has extended downward from milliohms to hundreds of microhms. Such low ohmic values present challenges to the user at many stages in their design and manufacturing processes.

This two-part series considers the nature of these challenges and suggests strategies to overcome them at various stages, including component selection, PCB layout design, verification of the ohmic value of unmounted components, and critical assembly processes. Each stage features potential pitfalls but also opportunities to quantify and minimize error and variation.

Although sub-milliohm chip resistors are still just chip resistors, ideal design strategies treat them as a separate class of component, embracing considerations and techniques that enable their successful use.

# **Component Selection**

# *Termination Styles*

When restricting the temperature sensitivity of a resistorbased current-sensing circuit, it's well-known that the total terminal resistance from copper, common to both the current-carrying circuit and the voltage-sense circuit, must be restricted as well. That's because this element of the total





measured resistance has a temperature coefficient of resistance (TCR) of +3900 ppm/°C, which contributes to the total TCR in proportion to the resistance ratio.

For example, a total terminal resistance of 100  $\mu\Omega$ , i.e., 50 µΩ at each end, for a 1-mΩ resistor contributes  $100 \mu\Omega/1000$  $\mu\Omega \times 3900$  ppm/°C = 390 ppm/°C to the TCR. This contrasts with the TCR of the resistance element itself, which is typically better than ±30 ppm/°C. Such separation between the current-carrying and voltage-sense circuits is referred to as a Kelvin connection, an issue that becomes clearly more important as the nominal ohmic value is reduced.

There's a spectrum of termination styles to address this problem. The most common is the Kelvin connectable twoterminal resistor *(Fig. 1a)*. While this is often the lowest-cost option, it places the onus on the PCB designer to realize a Kelvin connection in the PCB track layout (later we'll look in detail at how this may best be achieved). Such a component must have a low termination resistance since the Kelvin connection strategy necessarily ends at the surface of the termination.

*Figure 1b* shows an intermediate component type where four solder terminals are provided, but the separation of circuits doesn't extend all the way into the resistor element. *Figure 1c* shows a true Kelvin format where there's no currentcarrying termination whatsoever within the voltage-sense circuit. The latter two types offer error-proof PCB layout design and the lowest achievable magnitude of TCR, but generally it comes at a higher cost.

*Element Materials* 

Low-value resistors can be made from both thick- and thin-film materials, but the lowest values available in these technologies are in the multiple-milliohm range. Both types are relatively susceptible to damage from high-current surges. In the case of thick-film technology, the lowest values are associated with high TCR values of several hundred ppm/°C and thus are suited only to low precision use.

For these reasons, most current-sense chip resistors are

based on a bulk metal element. This may be either a foil supported on a substrate or a self-supporting metal element. Though the former option allows for the use of thin metal layers to achieve higher values, the latter lends itself to submilliohm values.

A range of alloys, each with differing resistivities, are selected by device designers to provide the required ohmic value within the dimensional constraints of the product. From the point of view of the user, the material choice is often unimportant, but there are two exceptions: one is the control of thermally generated errors, and the other is application for non-dc circuits.

A copper-terminated metal-element chip resistor contains at least two boundaries between dissimilar metals. These act as thermocouples and generate a thermoelectric voltage in the presence of a temperature gradient. Furthermore, they're connected in series, and because of the component's symmetry, they're of opposite polarity when the resistor element itself is the main heat source. As a result, if the temperature distribution across the chip resistor is symmetrical, any generated thermoelectric voltages will be cancelled out.

*Figure 2a* illustrates this balanced state in which the thermal voltages  $V_1$  and  $V_2$  are equal. *Figures 2b* and 2c show an example of imbalance due to the external influence of a heat source and a heatsink, respectively. This would lead to a finite value of  $V_1 - V_2$ , which would sum with the measured sense voltage and create a source of error.

In many designs, it's simply not possible to guarantee thermal symmetry under all operating conditions. In such a case, a chosen part should employ a resistance alloy with a low thermoelectric voltage against copper. These alloys contain manganese in a copper nickel alloy in which the proportion of copper exceeds 80%. The thermoelectric voltages generated across a junction with copper can be as low as  $3 \mu V$ /°C, which is an order of magnitude lower than for a copper nickel alloy.



2. Shown is a balanced state in which the thermal voltages V1 and V2 are equal (a), and examples of imbalance due to the external influence of a heat source (b) and a heat sink (c).

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3. Illustrated are an open-air format metal-alloy resistor (a), and a flatchip format metal-alloy resistor (b).

The second application-specific driver for resistance alloy selection is the need to avoid iron-bearing alloys in circuits where ac or rapid step changes in dc need to be tracked accurately, as this is not possible with ferromagnetic alloys.

# *Thermal Design Format*

An inherent problem with resistive current sensing is heat, generated at a rate proportional to the square of the current. This may need to be restricted for one of two reasons. First, the design must reduce the effect of temperature increase on the linearity of the component, which can stem from TCR or from thermoelectric voltage errors. Second, it's necessary to avoid overheating the resistance alloy, which can lead to irreversible ohmic-value change.

This consideration calls for careful thermal design of the assembly. It begins at the component selection stage in response to the basic decision as to where the heat generated should be dissipated; for example, in the air or in the copper PCB tracks. The answer to this depends on the overall thermal-management strategy.

A well-ventilated assembly—with either a high thermal loading already on the PCB or with temperature-sensitive components—would benefit from a resistor that dissipates heat into the air. Conversely, a PCB that's heatsinked, or has no excess of heat generation and no temperature-sensitive parts, can employ a resistor which dissipates heat mainly to the PCB tracks.

An example of a primarily air-dissipating open-air format is shown in *Figure 3a*. This can sustain a temperature rise of the hotspot above the solder joints well in excess of 100°C. Its flexible nature makes it virtually immune to temperature cycling or board flex stresses on the solder joints. An example of the primarily PCB dissipating flat-chip format is shown in *Figure 3b*. The design benefits from its low profile and is generally the lower-cost option.

# *Most Common Type*

After considering the many options of termination style, element material, and thermal design format, the most common type of sub-milliohm resistor is a two-terminal metalelement chip resistor. This resistor type will be considered hereafter in this article.

#### **PCB Layout Design**

*Near-Kelvin Connection*

The PCB layout design around a very-low-value resistor



4. Minimizing the conductive path shared between the current path and the voltage-sensing loop increases both the effective ohmic value and the TCR of the mounted part.



5. To achieve what's illustrated in Figure 4, connect the voltage-sense tracks to the inner edges of the solder pads.

is critical to its performance. The most important aspect of this design is the fact that four rather than two tracks must be provided to form a Kelvin connection, even where the component itself has only two terminals.

The aim is to minimize the conductive path shared between the current path and the voltage-sensing loop *(Fig. 4)*, which would increase both the effective ohmic value and the TCR of the mounted part. This may be achieved by connecting the voltage-sense tracks to the inner edges of the solder pads *(Fig. 5)*.

Designers also can take this a step further and split the voltage-sense pads from the current-path pads, so that the solder joints themselves are removed from the shared path, too *(Fig. 6)*. By using this method, it's possible to approach





the accuracy obtained from a true four-terminal resistor.

Furthermore, a study<sup>1</sup> by Analog Devices based on TT Electronics' ULR3 0.5-mΩ mounting-pad options has shown that a mounted value tolerance close to 1% may be achieved on a 1% tolerance component. This indicates low additional error due to mounting effects, using a centralized, isolated sense-pad design similar to that of *Figure 4c*.



7. Parallel connection requires equal distribution of current.



#### *Minimization of Sense-Loop Area*

A source of error involving high currents that are ac or changing dc is due to the voltage-sensing loop linking with changing magnetic fields. This can induce a noise signal superimposed on the desired voltage sense signal.

To reduce the noise, the loop area contained within the sense resistor, the two voltage-sense tracks, and the sense circuit input should be minimized. This means keeping the sense circuitry as close as possible to the sense resistor and running the voltage-sense tracks close to each other.

A good way to keep these tracks very close is to superimpose them in different PCB layers. Where long track runs are unavoidable, it's also possible to use periodic vias to cross over the tracks into alternate layers. On a PCB, this replicates the effect of a twisted-pair cable, which, by means of cancellation of induced voltages, allows the circuit to withstand the effect of any changing magnetic fields that have small variations across the spatial periodicity of the twisting.

*Connecting Multiple Resistors in Parallel*

Sometimes, designers are forced to use more than one current-sense resistor connected in parallel, either to meet a high power or surge rating, or to achieve an ohmic value lower than the minimum available. This is problematic but possible. Resistors may be connected in parallel with voltage-sense connections made to just one of the resistors, provided the track layout ensures equal distribution of current between all resistors.

For example, the position in the current trace where the resistors are placed should be well clear of bends or constrictions that could affect the distribution of current density *(Fig. 7)*. The goal is to ensure that the total track resistance in series with each resistor should be the same *(Fig. 8)*, so that the sensed resistor carries the required fraction of the total current.

Moreover, this ensures that the proportion of the total current carried by the sensed resistor doesn't vary with temperature. This would otherwise be the case with unequal



9. The general relationship between effective power rating and PCB 8. The total series track resistance should match for all resistors. copper area can be divided into three distinct regions.



10. The limiting factor of the internal thermal impedance may be lowered significantly by changing the orientation of the resistor. If the terminations are formed on the longer edges of the chip rather than the shorter edges, the solder joint width is approximately doubled and the maximum distance from film center to termination is approximately halved (a). TT Electronics ULR2N and ULR3N are examples of products that make use of this enhanced cooling method (b).

series track resistances due to the high TCR of the copper PCB tracks.

#### *Design for Heatsinking*

A flat-chip resistor dissipates more than 80% of its heat by conduction into PCB tracks, making it important to provide sufficient copper area to act as a heatsink. Copper area is, for this purpose, defined as the total area directly surrounding the solder pads, including the first two squares of connected tracks. *Figure 9* indicates the general relationship between effective power rating and PCB copper area.

In region (A), there's relatively low thermal conduction through copper connected to the pads, and conduction by substrate and convection to air predominate. In region (B), the copper connected to the pads acts as a heatsink to raise the effective power rating. In region (C), further increase in copper area gives diminishing returns, as the internal thermal impedance of the chip restricts the rating.

This limiting factor of the internal thermal impedance can be lowered significantly by changing the resistor's orientation. If the terminations are formed on the longer edges of the chip rather than the shorter edges, the solder joint width is approximately doubled and the maximum distance from film center to termination is approximately halved *(Fig. 10a)*. TT Electronics' ULR2N and ULR3N *(Fig. 10b)* are examples of products that use this enhanced cooling method.

The resistor datasheet should contain information on the mounting conditions used to obtain the rated power. This indicates the minimum copper area that should be provided by the designer.

# **Summary**

The growing use of sub-milliohm chip resistors for current sensing creates a spectrum of challenges for the designer and the process engineer. The component format should first be selected to support the chosen thermal-management approach, with metal-element flat-chip resistors having two

terminals being the most cost-effective solution. It's then essential to design the PCB tracks and pads to meet the needs of the Kelvin connection, heat dissipation, and avoidance of induced noise.

Part 2 of this series will address additional stages, including verification of the ohmic value of unmounted components and critical assembly processes.

# **References**

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